

# When Teachers are Lazy

(Tentative Title)

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# How did it Begin?

## *Research Question:*

How effectively can GPT models identify hand-drawn concepts by analyzing stroke coordinate data?

The hand-drawn concepts were to be extracted from the Google *Quick, Draw!*<sup>1</sup> dataset.

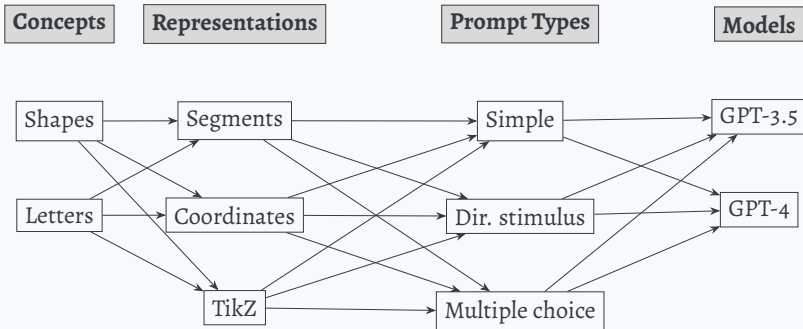
- Publicly available.
- 345 concepts (e.g., *apple*, *The Mona Lisa*, *pizza*).
- Stroke coordinates for 40M+ moderated drawings.

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<sup>1</sup>[quickdraw.withgoogle.com](https://quickdraw.withgoogle.com)

# How did it Begin? (cont.)

First, we conducted a basic experiment:



# How did it Begin? (cont.)

The prompt structure employed for **segments**, incorporating a **directional stimulus**, is as follows:

You will be provided with a set of line segments of a shape.

Each line segment is represented as `[ (x0, y0), (x1, y1) ]`, where `(x0, y0)` is the starting coordinate, and `(x1, y1)` is the final coordinate.

The line segments are given below, delimited by triple backticks:  
````{segments}````

Your task is to identify the polygon or letter represented by the figure based on the hint.

Hint: Possible polygons are: Triangle, Square, Rectangle, Pentagon, Hexagon, Octagon, Parallelogram, Right arrow, Diamond, Trapezoid or Star.  
Possible letters are: A, E, I, O, U.

# How did it Begin? (cont.)

Table: Accuracy of the GPT models in identifying “easy” concepts.

Concept	GPT-4	GPT-3.5
Square	100%	100%
Triangle	94%	100%
Pentagon	89%	89%
Hexagon	89%	83%
⋮	⋮	⋮
Parallelogram	0%	0%
Right arrow	0%	0%
A	79%	57%
E	43%	7%
I	36%	14%
O	7%	0%
U	0%	0%

The most effective method involved using either **segments** or **TikZ** with the prompting technique that presents **multiple choices** ( $72\% \leq \text{avg. acc.} \leq 88\%$ ).

# Concept's Complexity

We focused on the *Quick, Draw!* dataset. In this dataset, we assume that the **complexity of a drawing is related to the number of hand-drawn strokes it contains.**



(a) 2 strokes



(b) 5 strokes

Figure: Two hand-drawn representations of the concept *house*.

Using the number of strokes data, we can **sort concepts** and their hand-drawn images by their level of complexity.

# A (Potential) Machine Teaching Framework

## *Research Question:*

How many strokes are minimally required for GPT to identify the concept in a hand-drawn representation?

We thus define the teaching size (TS) of a given concept  $c$  as

$$\text{TS}(c) \approx \min_{w \in Q: L_m(R(w))=c} \text{size}(w), \quad (1)$$

where  $R$  is a representation of  $w$  (which could be either stroke coordinates [text-based] or an image[visual-based]), and  $\text{size}$  is a function that, e.g., returns the number of strokes of a given hand-drawn representation.

# The Experiment

We started by categorizing each hand-drawn image from the *Quick, Draw!* dataset into a **bin according to its level of complexity**.

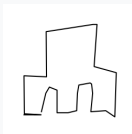
For every bin, we then **randomly select 50 hand-drawn representations** from the dataset.

For every hand-drawn image ( $\approx 345 \times 10 \times 50 = 172\,500$ ), we evaluated whether the given representation was **adequate for the learner (i.e., GPT) to identify and learn the concept**.

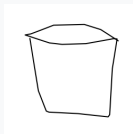
In addition to getting the TS for each concept, we can examine how **changes in complexity impact the learning accuracy**.



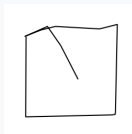
# The Results



(a) Car



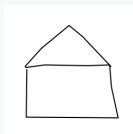
(b) Cup



(c) Envelope



(d) Golf club



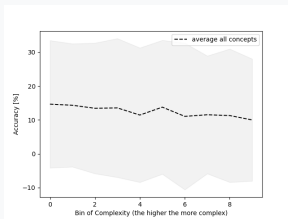
(e) House



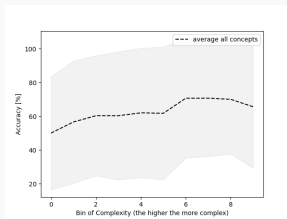
(f) Triangle

Figure: Minimal hand-drawn representations of a subset of concepts learned by the learner. (Representation as strokes coordinates.)

# The Results (cont.)



(a) Text-based



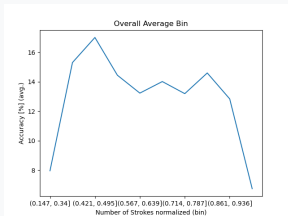
(b) Visual-based

Figure: Comparison, in terms of complexity, between the two representations.

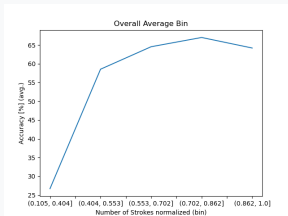
**Concept complexity:** *line* > *banana* > *triangle* > *square* > *envelope* = *house* > ... > *car* > *guitar* > *butterfly* > *piano*

**Concept complexity:** *line* > *stairs* > *triangle* > *golf club* > *square* > *banana* > ... > *candle* > *airplane* > *cup* > *apple*

# The Results (cont.)



(a) Text-based



(b) Visual-based

Figure: Comparison, in terms of complexity, between the two representations.

This behavior can be, to some extent, **similar to human identification capabilities**.

# The Results (cont.)

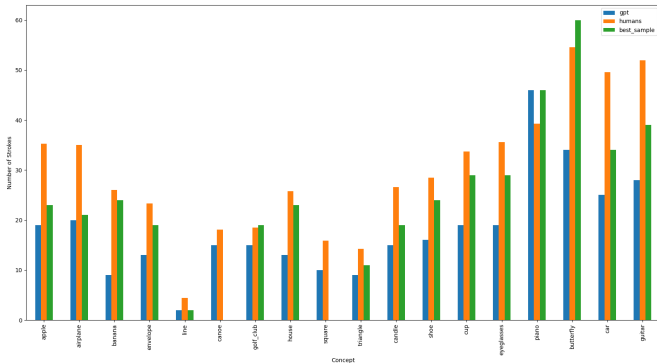


Figure: Comparison between the number of strokes used by humans versus the number of strokes the learner needed to identify a concept (text-based).

# The Final Research Question

The previous results pose the following question: “**How can GPT be used to understand fundamental teaching questions?**”.

*(Final) Research Question:*

How intrinsically difficult is teaching a concept based solely on its shape?

# The Final Machine Teaching Framework (cont.)

To answer this question, we can use the teaching size that we discussed earlier:

$$\text{TS}(c) \approx \min_{w \in Q: L_m(R(w))=c} \text{size}(w), \quad (2)$$

where  $R$  is a representation of  $w$ , either an image  $\text{IMG}(w)$  or the segments given by  $\text{RDP}_\epsilon(w)$ <sup>2</sup>.

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<sup>2</sup>Ramer–Douglas–Peucker algorithm.

# A Note on the Use of GPT

Assume the teaching size would be given as follows:

$$TS(c) = \min_{w:L(w)=c} size(w) \quad (3)$$

and that the learner would be Bayesian posterior:

$$\begin{aligned} L_p(w) &= \arg \max_c p(c|w) = \arg \max_c \frac{p(w|c)p(c)}{p(w)} \\ &= \arg \max_c p(w|c)p(c) = \arg \max_c p(w, c) \end{aligned} \quad (4)$$

or a Bayesian likelihood estimator:

$$L_l(w) = \arg \max_c p(w|c). \quad (5)$$

Since  $p(w|c)$ ,  $p(c)$ , and  $TS(c)$  are unknown, and we have a poor estimation of  $p(w, c)$ , we must use a proxy for  $L$  (thus,  $L_m$ ).

# The Experiment Algorithm

**procedure** LAZYTEACHER( $c, n$ ), where  $c$  is a given concept and  $n$  the number of samples

$D_{\text{raw}} \leftarrow \text{DownloadRawData}(c)$

$D_{\text{filtered}} \leftarrow \{d \in D_{\text{raw}} \mid d.\text{recognized} = \text{True}\}$

$D \leftarrow \text{Sample}(D_{\text{filtered}}, n)$

$D_{\text{simple}} \leftarrow \{\text{RDP}(d, 2) \mid d \in D\}$

$P \leftarrow \text{ObtainPrototypes}(D_{\text{simple}})$

$\text{TS}_{\text{coord}} \leftarrow \infty$

$\text{TS}_{\text{img}} \leftarrow \infty$

**for** each prototype  $p \in P$  **do**

$\epsilon \leftarrow 2$

$p_{\text{simple}} \leftarrow p$

**repeat**

$\hat{c}_{\text{coord}} \leftarrow \text{GPTPrompt}(p_{\text{simple}}.\text{coordinates})$

**if** match( $\hat{c}_{\text{coord}}, c$ ) **then**

$\text{TS}_{\text{coord}} \leftarrow \min(\text{TS}_{\text{coord}}, |\text{Segments}(p_{\text{simple}})|)$

**end if**

$\hat{c}_{\text{img}} \leftarrow \text{GPTPrompt}(p_{\text{simple}}.\text{image})$

**if** match( $\hat{c}_{\text{img}}, c$ ) **then**

$\text{TS}_{\text{img}} \leftarrow \min(\text{TS}_{\text{img}}, |\text{Segments}(p_{\text{simple}})|)$

**end if**

$\epsilon \leftarrow \epsilon + 1$

$p_{\text{simple}} \leftarrow \text{RDP}(p, \epsilon)$

**until** CannotSimplifyFurther( $p_{\text{simple}}, \epsilon$ )  $\triangleright$  (i.e., when

all segments only have two coordinates)

**end for**

**return**  $\text{TS}_{\text{coord}}, \text{TS}_{\text{img}}$

**end procedure**



# Prototypes (Possible Approaches)

The aim is to obtain minimal hand-drawn representations that are still sufficiently detailed to be **representative of the concepts they illustrate**.

We pretend to explore **different methods**, such as:

- **Mean shift clustering**<sup>3</sup> using the latent representation obtained from a convolutional autoencoder.
- **CLIP (Contrastive Language–Image Pre-training)**<sup>4</sup>, and select the top- $n$  highest CLIP scores.

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<sup>3</sup>Georgescu, Shimshoni, and Meer, “Mean shift based clustering in high dimensions: A texture classification example”.

<sup>4</sup>Radford et al., *Learning transferable visual models from natural language supervision*.

# Conclusion

- **Machine Teaching Framework:** We established the Teaching Size as the minimal number of strokes necessary for a learner to recognize a given concept.
- **Algorithm:** We developed the algorithm to minimize the number of strokes (RDP) within a multimodal learning environment.
- **Research Direction:** (1) How can GPT be used to understand fundamental teaching questions? (2) How intrinsically difficult is teaching a concept based solely on its shape?